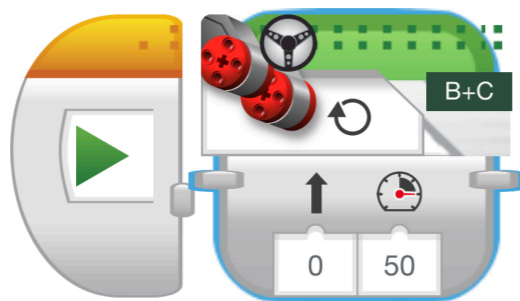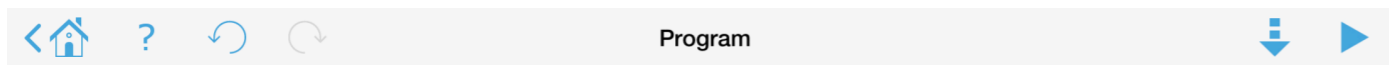# How to use your sensor(s) readings

REMEMBER your robot configuration:

Port 2 - Right colour sensor
Port 3 Left colour sensor
Port 4 - Ultrasonic Sensor
Port B - Left motor
Port C - Right Motor

While your robot is connected to your device, you have a live look at what your robot's sensors 'see'.